## Tamkang University Academic Year 114, 1st Semester Course Syllabus

Course Title	INTRODUCTION TO AUTONOMOUS DRIVING	Instructor	JOE-MEI FENG
Course Class	TEIEM1A  MASTER'S PROGRAM IN INTELLIGENT  COMPUTING AND APPLICATION, DEPARTMENT  OF COMPUTER SCIENCE AND INFORMATION	Details	<ul><li>General Course</li><li>Selective</li><li>One Semester</li><li>3 Credits</li></ul>
Relevance to SDGs	ENGINEERING, 1A SDG8 Decent work and economic growth SDG9 Industry, Innovation, and Infrastructure		

#### Departmental Aim of Education

- I. Cultivate the ability to conduct independent research and problem solving.
- ■. Strengthen creativity and research capacity.
- ${\rm I\hspace{-.1em}I\hspace{-.1em}I}$ . Build profound professional knowledge in networking and communication.
- IV. Engage in self-directed lifelong learning.

### Subject Departmental core competences

- A. Independent problem solving ability.(ratio:20.00)
- B. Independent innovative thinking ability.(ratio:20.00)
- C. Research paper writing and presentation ability.(ratio:20.00)
- D. Research &development (R&D) ability in networking and communication.(ratio:10.00)
- E. Project execution and control ability.(ratio:10.00)
- F. Lifelong self-directed learning ability.(ratio:20.00)

#### Subject Schoolwide essential virtues

- 1. A global perspective. (ratio:10.00)
- 2. Information literacy. (ratio:20.00)
- 3. A vision for the future. (ratio:10.00)
- 4. Moral integrity. (ratio:10.00)
- 5. Independent thinking. (ratio:10.00)
- 6. A cheerful attitude and healthy lifestyle. (ratio:10.00)
- 7. A spirit of teamwork and dedication. (ratio:20.00)
- 8. A sense of aesthetic appreciation. (ratio:10.00)

# Course Introduction

This course introduces autonomous driving systems, covering perception, localization, path planning, decision-making, control, and in-vehicle communication. Students will learn to know sensors (LiDAR, radar, camera, GPS, IMU), simulation platforms (CARLA, LGSVL, SUMO), and open-source frameworks (Autoware, Apollo). Emphasis is on practical implementation, system integration, and deployment on in-vehicle computing platforms. Assessment includes projects, simulations, and presentations.

# The correspondences between the course's instructional objectives and the cognitive, affective, and psychomotor objectives.

Differentiate the various objective methods among the cognitive, affective and psychomotor domains of the course's instructional objectives.

I. Cognitive: Emphasis upon the study of various kinds of knowledge in the cognition of the course's veracity, conception, procedures, outcomes, etc.

II. Affective: Emphasis upon the study of various kinds of knowledge in the course's appeal, morals, attitude, conviction, values, etc.

III.Psychomotor: Emphasis upon the study of the course's physical activity and technical manipulation.

No.	Teaching Objectives	objective methods
1	Through the study of autonomous driving, students will acquire	Cognitive
	foundational knowledge related to autonomous vehicle	
	technologies and develop the essential competencies required for	
	research and development. They will be prepared to pursue further	
	academic inquiry or professional work in the field, gain a global	
	perspective on the autonomous driving industry, and recognize the	
	importance of teamwork and collaboration.	

The correspondences of teaching objectives: core competences, essential virtues, teaching methods, and assessment

No.	Core Competences	Essential Virtues	Teaching Methods	Assessment
1	ABCDEF	12345678	Lecture, Practicum	Study Assignments, Discussion(including classroom and online), Practicum, Report(including oral and written), Activity Participation

#### Course Schedule

Week Date Course Contents		Course Contents	Note

1	114/09/15 ~ 114/09/21	Course introduction, SAE levels, system overview; lecture & case discussion.	
2	114/09/22 ~ 114/09/28	Sensor principles (Camera, LiDAR, Radar, GPS/IMU, calibration); demos & exercises.	
3	114/09/29 ~ 114/10/05	Visual perception (lane detection, object recognition, deep learning); image detection experiments.	
4	114/10/06 ~ 114/10/12	Sensor fusion (EKF/UKF, multi-modal fusion, tracking); ROS examples.	
5	114/10/13 ~ 114/10/19	Localization & mapping I (GNSS, GPS, IMU , Camera, LiDAR odometry)	
6	114/10/20 ~ 114/10/26	Localization & mapping II (SLAM, HD Map, urban localization); fusion, SLAM demo.	
7	114/10/27 ~ 114/11/02	Path planning I (A*, D*, RRT*); algorithm exercises.	
8	114/11/03 ~ 114/11/09	Path planning II (dynamic environment, decision-making, reinforcement learning); planning simulation.	
9	114/11/10 ~ 114/11/16	Control systems I (longitudinal/lateral control, PID); Carla following experiment.	參與工學院機械系舉辦之 熊貓講座活動
10	114/11/17 ~ 114/11/23	Control systems II (MPC, vehicle dynamics); MPC demo.	
11	114/11/24 ~ 114/11/30	Embedded Systems & Automotive Chips; Software Architecture & Communication Protocols; (ROS2, DDS; CAN, Ethernet)	
12	114/12/01 ~ 114/12/07	Simulation softwares; CARLA, LGSVL, Prescan, CarSim; Testing & validation (SIL/HIL, scenario generation); driving simulation; Docker	
13	114/12/08 ~ 114/12/14	Extension Topic: Autonomous Parking	
14	114/12/15 ~ 114/12/21	Extension Topic: Autonomous Driving	
15	114/12/22 ~ 114/12/28	Extension Topic: AR/VR; Robotics	
16	114/12/29 ~ 115/01/04	Presentation	
17	115/01/05 ~ 115/01/11	Presentation	
18	115/01/12 ~ 115/01/18	Presentation	

Key capabilities	self-directed learning  International mobility  Information Technology  Problem solving  Interdisciplinary		
Interdisciplinary	STEAM course (S:Science, T:Technology, E:Engineering, M:Math, A field:Integration of Art and Humanist)  Competency-based education 'competency exploration' sustained competency or global issues STEEP (Society, Technology, Economy, Environment, and Politics)  In addition to teaching content of the teacher's professional field, integrate other subjects or invite experts and scholars in other fields to share knowledge or teaching		
Distinctive teaching	Special/Problem-Based(PBL) Courses		
Course Content	Computer programming or Computer language (students have hands-on experience in related projects) Intellectual Property (learning intellectual property) Logical Thinking Environmental Safety AI application		
Requirement	Use is allowed if properly attributed.		
Textbooks and Teaching Materials	Self-made teaching materials:Presentations, Handouts Using teaching materials from other writers:Textbooks, Presentations, Handouts, Videos, Worksheets		
References			
Grading Policy	<ul> <li>◆ Attendance: 60.0 % ◆ Mark of Usual: 40.0 % ◆ Midterm Exam: %</li> <li>◆ Final Exam: %</li> <li>◆ Other ⟨ ⟩: %</li> </ul>		
This syllabus may be uploaded at the website of Course Syllabus Management <a href="https://web2.ais.tku.edu.tw/csp">https://web2.ais.tku.edu.tw/csp</a> or through the link of Course Syllabus Up on the home page of TKU Office of Academic Affairs at <a href="http://www.acad.tku.edu.tw/CS/main.php">http://www.acad.tku.edu.tw/CS/main.php</a> .  **"Adhere to the concept of intellectual property rights" and "Do not ill photocopy, download, or distribute." Using original textbooks is advisits a crime to improperly photocopy others' publications.			

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